Biped Robot

Model Number[WALKING_BP1-KT]
Biped Robot

· Robot chassis and HS-5645 servos only; no electronics
· The biped legs feature 6 degrees of freedom
· No of DOF per leg = 6
· Servo motion control = local closed loop
· Height (as pictured) = 13.5"
· Width (as pictured) = 7.5"
· Ground Clearance = 5"
· Weight (without batteries) = 37.6 oz
· Range of motion per axis = 180 degrees
· Accuracy of motion per axis = Servo controller dependant (usually .72 degrees)
· Servo voltage = 6 vdc
**Model Number[WALKING_BP2-KT]**

Biped Robot

- Robot chassis and HS-5475 servos only; no electronics
- The biped legs feature 6 degrees of freedom
- No of DOF per leg = 6
- Servo motion control = local closed loop
- Height (as pictured) = 13.5"
- Width (as pictured) = 7.5"
- Ground Clearance = 5"
- Weight (without batteries) = 37.6 oz
- Range of motion per axis = 180 degrees
- Accuracy of motion per axis = Servo controller dependant (usually .72 degrees)
- Servo voltage = 6 vdc

**Model Number[WALKING_BP-NS]**

Biped Robot

- Robot chassis only; no servos; no electronics
- The biped legs feature 6 degrees of freedom
- No of DOF per leg = 6
- Servo motion control = local closed loop
- Height (as pictured) = 13.5"
- Width (as pictured) = 7.5"
- Ground Clearance = 5"
- Weight (without batteries) = 37.6 oz
- Range of motion per axis = 180 degrees
· Accuracy of motion per axis = Servo controller dependant (usually .72 degrees)

· Servo voltage = 6 vdc