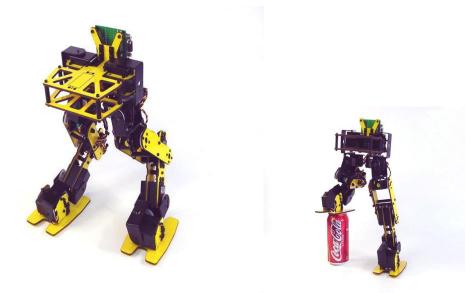**Biped Robot**

Model Number[WALKING_BP1-KT]
Biped Robot

· Robot chassis and HS-5645 servos only; no electronics

· The biped legs feature 6 degrees of freedom

· No of DOF per leg = 6

· Servo motion control = local closed loop

· Height (as pictured) = 13.5"

· Width (as pictured) = 7.5"

· Ground Clearance = 5"

· Weight (without batteries) = 37.6 oz

· Range of motion per axis = 180 degrees

· Accuracy of motion per axis = Servo controller dependant (usually .72 degrees)

· Servo voltage = 6 vdc

Model Number[WALKING_BP2-KT]
Biped Robot

· Robot chassis and HS-5475 servos only; no electronics

· The biped legs feature 6 degrees of freedom

· No of DOF per leg = 6

· Servo motion control = local closed loop

· Height (as pictured) = 13.5"

· Width (as pictured) = 7.5"

· Ground Clearance = 5"

· Weight (without batteries) = 37.6 oz

· Range of motion per axis = 180 degrees

· Accuracy of motion per axis = Servo controller dependant (usually .72 degrees)

· Servo voltage = 6 vdc

Model Number[WALKING_BP-NS]
Biped Robot

· Robot chassis only; no servos; no electronics

· The biped legs feature 6 degrees of freedom

· No of DOF per leg = 6

· Servo motion control = local closed loop

· Height (as pictured) = 13.5"

· Width (as pictured) = 7.5"

· Ground Clearance = 5"

· Weight (without batteries) = 37.6 oz

· Range of motion per axis = 180 degrees

· Accuracy of motion per axis = Servo controller dependant (usually .72 degrees)

· Servo voltage = 6 vdc